

Lecture 2: Spatial Linear Regression Models

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2.1. Introduction

Lecture 2 introduces popular spatial linear regression models and their estimation through quasi maximum likelihood (QML) method, and GM or GMM method, which include the linear regression models with

- 1 spatial lag (SL) dependence,
- 2 spatial error (SE) dependence,
- 3 both SL and SE (SLE),

Where spatial Durbin (SD) effect can be added to any of the three models.

- Asymptotic properties of the QML estimators are presented.
- Method of estimating standard errors of the QMLE is introduced.
- Finite sample performance of the QML-based methods is discussed based on Monte Carlo results.
- Two examples are presented to illustrate the applications of QML-based methods.

2.2. SLR Model with SE Dependence

Model. Spatial linear regression (SLR) model with spatial error (SE) dependence, or the SE model in short, takes the following form:

$$Y_n = X_n\beta + u_n, \quad u_n = \rho W_n u_n + \epsilon_n, \quad (2.1)$$

where the SE structure is a **spatial autoregressive** (SAR) process. It can also be a **spatial moving average** (SMA) process: $u_n = \rho W_n \epsilon_n + \epsilon_n$,

- Y_n : $n \times 1$ vector of observations on n spatial units,
- X_n : an $n \times k$ matrix containing the values of k regressors,
- W_n : $n \times n$ matrix summarizing interactions among n spatial units, called the **spatial weight matrix** or the **spatial interaction matrix**,
- ϵ_n : $n \times 1$ vector of independent and identically distributed (iid) idiosyncratic errors with mean zero and variance σ^2 ,
- ρ : the **spatial error parameter**,
- β : $k \times 1$ vector of regression coefficients.

Durbin-SE Model. The model (2.1) can be extended by adding a spatial Durbin term $W_n X_n^*$, where X_n^* contains **some** regressors, referred to in this course as **Durbin-SE model**:

$$Y_n = X_n \beta + W_n X_n^* \beta^* + u_n, \quad u_n = \rho W_n u_n + \epsilon_n. \quad (2.2)$$

The term '**spatial Durbin model**' was first appeared in Anselin (1988) for its analogy with Durbin (1960) for time series. See also Elhorst (2014, p.7).

- Elhorst (2014) interprets the spatial Durbin effect as the *exogenous interaction effects*, where the dependent variable of a particular unit depends on independent variables of other units.
- By defining a new regressor matrix $\mathbb{X}_n = [X_n, W_n X_n^*]$, and a new vector of regression coefficients $\beta = (\beta', \beta^{*'})'$, Durbin-SE model has the same form as the regular SE model, and hence inference methods remain the same.
- However, a problem of particular interest is to test the existence of spatial Durbin effect, i.e., testing $H_0: \beta^* = 0$, which can be carried out based on the usual tests for covariate effects, to be presented in Lecture 3.

2.2.1. QML estimation of SE model

For QML estimation of spatial models, the following results are useful:

(i) An n -dimensional random vector \mathbf{Y} is said to have a multivariate normal distribution with mean $\boldsymbol{\mu}$ and variance-covariance (VC) matrix $\boldsymbol{\Sigma}$, denoted as $N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, if its joint probability density function (pdf) takes the form:

$$f(\mathbf{y}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{n/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{y} - \boldsymbol{\mu})' \boldsymbol{\Sigma}^{-1} (\mathbf{y} - \boldsymbol{\mu})\right). \quad (2.3)$$

where $|\cdot|$ denotes the determinant of a square matrix.

(ii) For two $n \times n$ matrices A and B , and a scalar c :

$$|A'| = |A|, \quad |A^{-1}| = |A|^{-1}, \quad |cA| = c^n |A|, \quad |AB| = |A||B|;$$

(iii) For a matrix function $A(\rho)$ of scalar ρ , positive definite (p.d.),

$$\frac{\partial}{\partial \rho} A(\rho)^{-1} = -A(\rho)^{-1} \left[\frac{\partial}{\partial \rho} A(\rho) \right] A(\rho)^{-1}, \quad \text{Horn and Johnson (1985).}$$

$$\frac{\partial}{\partial \rho} \log |A(\rho)| = \text{tr}[A(\rho)^{-1} \frac{\partial}{\partial \rho} A(\rho)], \quad \text{tr}(\cdot) = \text{trace of a matrix.}$$

Now, define $B_n(\rho) = I_n - \rho W_n$. Then, $u_n = B_n^{-1}(\rho)\epsilon_n$, and

$$\Sigma_n = \text{Var}(u_n) = \sigma^2 B_n^{-1}(\rho) B_n'^{-1}(\rho).$$

By (2.3), the **quasi Gaussian loglikelihood function** of $\theta = (\beta', \sigma^2, \rho)'$ for the SE or Durbin-SE model, **as if** $\epsilon_{n,i}$ are iid normal, is given by,

$$\ell_n(\theta) = -\frac{n}{2} \log(2\pi\sigma^2) + \log |B_n(\rho)| - \frac{1}{2\sigma^2} u_n'(\beta) B_n'(\rho) B_n(\rho) u_n(\beta). \quad (2.4)$$

where $u_n(\beta) = Y_n - X_n\beta$. It is assumed: $|B_n(\rho)| > 0$, and $B_n^{-1}(\rho)$ exists.

- Maximizing $\ell_n(\theta)$ gives the MLE $\hat{\theta}_n$ of θ if the errors are indeed Gaussian, otherwise the QMLE.
- Letting $G_n(\rho) = W_n B_n^{-1}(\rho)$, maximizing $\ell_n(\theta)$ is equivalent to solving $S_n(\theta) = 0$, where the score function has the form:

$$S_n(\theta) = \frac{\partial}{\partial \theta} \ell_n(\theta) = \begin{cases} \frac{1}{\sigma^2} X_n' B_n'(\rho) B_n(\rho) u_n(\beta), \\ \frac{1}{2\sigma^4} u_n'(\beta) B_n'(\rho) B_n(\rho) u_n(\beta) - \frac{n}{2\sigma^2}, \\ \frac{1}{\sigma^2} u_n'(\beta) B_n'(\rho) W_n u_n(\beta) - \text{tr}[G_n(\rho)]. \end{cases} \quad (2.5)$$

The QML estimation process proceeds as follows:

- Solving the first two sets of equations of (2.5) for a given ρ gives the constrained QMLEs of β and σ^2 ,

$$\tilde{\beta}_n(\rho) = [X_n' B_n'(\rho) B_n(\rho) X_n]^{-1} X_n' B_n'(\rho) B_n(\rho) Y_n, \text{ and} \quad (2.6)$$

$$\tilde{\sigma}_n^2(\rho) = \frac{1}{n} Y_n' B_n'(\rho) M_n(\rho) B_n(\rho) Y_n, \quad (2.7)$$

where $M_n(\rho) = I_n - B_n(\rho) X_n [X_n' B_n'(\rho) B_n(\rho) X_n]^{-1} X_n' B_n'(\rho)$.

- The concentrated log-likelihood function for ρ upon substituting the constrained QMLEs $\tilde{\beta}_n(\rho)$ and $\tilde{\sigma}_n^2(\rho)$ into $\ell(\theta)$:

$$\ell_n^c(\rho) = -\frac{n}{2} [\log(2\pi) + 1] + \log |B_n(\rho)| - \frac{n}{2} \log(\tilde{\sigma}_n^2(\rho)). \quad (2.8)$$

- Maximising $\ell_n^c(\rho)$ numerically gives the unconstrained QMLE $\hat{\rho}_n$ of ρ ,
- which upon substitutions gives the unconstrained QMLEs of β and σ^2 as, $\hat{\beta}_n \equiv \tilde{\beta}_n(\hat{\rho}_n)$ and $\hat{\sigma}_n^2 \equiv \tilde{\sigma}_n^2(\hat{\rho}_n)$.
- Thus, the QMLE of the full parameter vector θ is $\hat{\theta}_n = (\hat{\beta}_n', \hat{\sigma}_n^2, \hat{\rho}_n)'$.

Let θ_0 be the true value of the parameter vector θ that generates the data; $E(\cdot)$ and $\text{Var}(\cdot)$ correspond to θ_0 ; and $B_n \equiv B_n(\lambda_0)$, $G_n \equiv G_n(\lambda_0)$, etc.

Theorem 2.1. Under regularity conditions, we have $\hat{\theta}_n \xrightarrow{P} \theta_0$, and

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{D} N(0, \lim_{n \rightarrow \infty} n\mathcal{J}_n^{-1}\mathcal{I}_n\mathcal{J}_n^{-1}), \quad (2.9)$$

(Liu & Yang 2015a), where $\mathcal{J}_n = -E[\frac{\partial}{\partial \theta} S_n(\theta_0)]$ and $\mathcal{I}_n = \text{Var}[S_n(\theta_0)]$, with

$$\mathcal{J}_n = \begin{pmatrix} \frac{1}{\sigma_0^2} X_n' B_n' B_n X_n & 0 & 0 \\ \sim & \frac{n}{2\sigma_0^4} & \frac{1}{\sigma_0^2} \text{tr}(G_n) \\ \sim & \sim & \text{tr}(G_n^s G_n) \end{pmatrix}, \text{ and} \quad (2.10)$$

$$\mathcal{I}_n = \begin{pmatrix} \frac{1}{\sigma_0^2} X_n' B_n' B_n X_n & \frac{1}{2\sigma_0^3} \gamma_0 X_n' B_n' \iota_n & \frac{1}{\sigma_0} \gamma_0 X_n' B_n' g_n \\ \sim & \frac{n}{4\sigma_0^4} (\kappa_0 + 2) & \frac{1}{2\sigma_0^2} (\kappa_0 + 2) \text{tr}(G_n) \\ \sim & \sim & \kappa_0 g_n' g_n + \text{tr}(G_n^s G_n) \end{pmatrix}, \quad (2.11)$$

where ι_n is a vector of ones, γ_0 and κ_0 are the measures of skewness and excess kurtosis of $\epsilon_{n,i}$, $g_n = \text{diagv}(G_n)$, $G_n = G_n(\rho_0)$, and $G_n^s = G_n + G_n'$.

Remarks:

- $\text{diagv}(G_n)$ forms a column vector by the diagonal elements of G_n .
- Note that in deriving the last component (the ρ - ρ component) of \mathcal{J}_n , we have used the following matrix identity (given above):

$$\frac{\partial}{\partial \rho} B_n^{-1}(\rho) = -B_n^{-1}(\rho) \left[\frac{\partial}{\partial \rho} B_n(\rho) \right] B_n^{-1}(\rho). \quad (2.12)$$

- Clearly, when $\epsilon_{n,i}$ are iid normal, $\gamma_0 = \kappa_0 = 0$, and the asymptotic result reduces to $\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{D} N(0, \lim_{n \rightarrow \infty} n\mathcal{J}_n^{-1})$.

For deriving the expression for $\mathcal{I}_n = \text{Var}[\mathbf{S}_n(\theta_0)]$, we have by (2.5),

$$\mathbf{S}_n(\theta_0) = \begin{cases} \frac{1}{\sigma_0^2} X_n' B_n' \epsilon_n, \\ \frac{1}{2\sigma_0^4} \epsilon_n' \epsilon_n - \frac{n}{2\sigma_0^2}, \\ \frac{1}{\sigma_0^2} \epsilon_n' G_n \epsilon_n - \text{tr}(G_n), \end{cases}$$

of which the elements are linear or quadratic forms in ϵ_n .

Based on the expression of $S_n(\theta_0)$ and using the following lemma, one can easily derive the analytical expression for $\mathcal{I}_{ns} = \text{Var}[S_n(\theta_0)]$.

Lemma 2.1. Let A_n and B_n be $n \times n$ non-stochastic matrices and c_n be $n \times 1$ non-stochastic vector. For $n \times 1$ random vector ϵ_n of iid elements with mean 0, variance σ_0^2 , skewness γ_0 , and finite excess kurtosis κ_0 , we have

$$(i) \text{Cov}(c_n' \epsilon_n, \epsilon_n' A_n \epsilon_n) = \sigma_0^3 \gamma_0 c_n' a_n,$$

$$(ii) \text{Cov}(\epsilon_n' A_n \epsilon_n, \epsilon_n' B_n \epsilon_n) = \sigma_0^4 \kappa_0 a_n' b_n + \sigma_0^4 \text{tr}(A_n B_n^s),$$

where $a_n = \text{diagv}(A_n)$, $b_n = \text{diagv}(B_n)$, and $B_n^s = B_n' + B_n$.

Note from Lemma 2.1 (ii), we can obtain $\text{Var}(\epsilon_n' A_n \epsilon_n)$ by letting $A_n = B_n$.

With the results of Theorem 2.1, the asymptotic variance-covariance (VC) matrix $\mathcal{J}_n^{-1}\mathcal{I}_n\mathcal{J}_n^{-1}$ of $\hat{\theta}_n$ is estimated as follows:

- 1 estimate \mathcal{J}_n by $\hat{\mathcal{J}}_n = \mathcal{J}_n(\hat{\theta}_n)$,
- 2 estimate \mathcal{I}_n by $\hat{\mathcal{I}}_n = \mathcal{I}(\hat{\theta}_n)$, **the plug-in estimators**,
- 3 and estimate γ_0 and κ_0 in \mathcal{I}_n by the sample skewness and excess kurtosis of the **QML residuals**: $\hat{\epsilon}_n = \epsilon_n(\hat{\rho}_n, \hat{\beta}_n) = B_n(\hat{\rho}_n)(Y_n - X_n\hat{\beta}_n)$.

The square roots of the diagonal elements of $\mathcal{J}_n^{-1}(\hat{\theta}_n)\mathcal{I}_n(\hat{\theta}_n)\mathcal{J}_n^{-1}(\hat{\theta}_n)$ give the estimated standard errors of $\hat{\theta}_n$, robust against nonnormality.

- t -ratios for the elements of θ_0 can then be constructed, from which one can
- judge whether the elements of θ_0 are significantly different from 0, and thus
- make a conclusion on whether a covariate or a spatial effect is significant.

2.2.2. GLS-GM estimation of SE model

A hybrid method, combination of generalized least squares (GLS) and generalized moments (GM), for estimating the SE model is introduced by Kelejian and Prucha (1999). The ideas are

- first to develop GM estimators $\tilde{\rho}_n$ and $\tilde{\sigma}_n^2$ for ρ and σ^2 , based on a consistent 'predictor' \tilde{u}_n for u_n ;
- then to estimate $\Sigma_n = \text{Var}(u_n)$ by $\tilde{\Sigma}_n = \tilde{\sigma}_n^2 B_n^{-1}(\tilde{\rho}_n) B_n^{-1}(\tilde{\rho}_n)$, leading to a feasible GLS estimate for β as

$$\tilde{\beta}_n = (X_n' \tilde{\Sigma}_n^{-1} X_n)^{-1} X_n' \tilde{\Sigma}_n^{-1} Y_n;$$

- Under typical conditions, the GLS estimator of β based on Σ_n is consistent and asymptotically normal;
- Under additional conditions, e.g., $\tilde{\rho}_n$ and $\tilde{\sigma}_n^2$ are consistent, the feasible GLS estimator is asymptotically equivalent to the GLS estimator, and thus is also consistent and asymptotically normal.

GM estimation. The generalized moments (GM) estimation of ρ and σ^2 is based on the following three moment conditions:

$$\begin{aligned}E\left(\frac{1}{n}\epsilon'_n\epsilon_n\right) &= \sigma^2, \\E\left(\frac{1}{n}\epsilon'_n W'_n W_n \epsilon_n\right) &= \sigma^2 n^{-1} \text{tr}(W'_n W_n), \\E\left(\frac{1}{n}\epsilon'_n W'_n \epsilon_n\right) &= 0.\end{aligned}$$

By $\epsilon_n = B_n(\rho)u_n$, we obtain the following sample moment conditions:

$$\mathbf{g}_n(\rho, \sigma^2) = \begin{cases} \frac{1}{n}\tilde{u}'_n B'_n(\rho) B_n(\rho)\tilde{u}_n - \sigma^2, \\ \frac{1}{n}\tilde{u}'_n B'_n(\rho) W'_n W_n B_n(\rho)\tilde{u}_n - \frac{1}{n}\sigma^2 \text{tr}(W'_n W_n), \\ \frac{1}{n}\tilde{u}'_n B'_n(\rho) W'_n B_n(\rho)\tilde{u}_n. \end{cases}$$

The GM estimators of ρ and σ^2 are thus:

$$(\tilde{\rho}_n, \tilde{\sigma}_n^2) = \text{argmin} [\mathbf{g}'_n(\rho, \sigma^2)\mathbf{g}_n(\rho, \sigma^2)],$$

Remark: \tilde{u}_n can be the ordinary least squares (OLS) residuals, i.e., the residuals obtained from regressing Y_n on X_n (Kelejian and Prucha, 1999).

2.2.3. Finite sample performance of the QMLE of SE model

Intuitively, spatial error dependence causes the disturbances u_n to lose 'a lot' of degrees of freedom (df). As a result, the QML estimation of ρ and σ^2 may suffer from finite sample bias. This issue needs attention.

Liu and Yang (2015a) demonstrate based on Monte Carlo experiments:

- $\hat{\rho}_n$ can be severely downward biased, but the bias of $\hat{\rho}_n$ does not spill over much to $\hat{\beta}_n$;
- However, the bias of $\hat{\rho}_n$ does spill over to the estimate of $\text{Var}(\hat{\beta}_n)$;
- This makes the usual t -ratios for (the elements of) β_0 more variable than $N(0, 1)$ and inferences for β_0 based on it unreliable.

From the asymptotic results given in (2.9)-(2.11), we see that $\hat{\beta}_n$ follows asymptotically $N(\beta_0, \sigma_0^2(X_n' B_n' B_n X_n)^{-1})$. Thus, inference for the linear contrast in β_0 : $c_0' \beta_0$, is carried out based on the following t -ratio:

$$t_{\text{SE}}(\beta_0) = \frac{c_0' \hat{\beta}_n - c_0' \beta_0}{\sqrt{\hat{\sigma}_n^2 c_0' [X_n' B_n'(\hat{\rho}_n) B_n(\hat{\rho}_n) X_n]^{-1} c_0}}. \quad (2.13)$$

From the t -ratio given above, we see that

- downward bias of $\hat{\rho}_n$ causes $\hat{\sigma}_n^2$ to be downward biased, and
- severe bias of $\hat{\rho}_n$ may cause $X_n' \hat{B}_n' \hat{B}_n X_n$ to be severely biased for the estimation of $X_n' B_n' B_n X_n$ as seen from the expression:

$$X_n' B_n' (\hat{\rho}_n) B_n (\hat{\rho}_n) X_n = X_n' B_n' B_n X_n - (\hat{\rho}_n - \rho_0) X_n' (W_n' B_n + B_n' W_n) X_n + (\hat{\rho}_n - \rho_0)^2 X_n' W_n' W_n X_n.$$

- If $X_n' (W_n' B_n + B_n' W_n) X_n \geq 0$, then

$X_n' B_n' (\hat{\rho}_n) B_n (\hat{\rho}_n) X_n$ **overestimates** $X_n' B_n' B_n X_n$,

$\hat{\sigma}_n^2 c_0' [X_n' B_n' (\hat{\rho}_n) B_n (\hat{\rho}_n) X_n]^{-1} c_0$ **underestimates** $\text{Var}(c_0' \hat{\beta}_n)$.

- $\Rightarrow t_{SE}(\beta_0)$ tends to be 'larger' than $N(0, 1)$ (or more variable),
 \Rightarrow confidence interval for $c_0' \beta_0$ has **low coverage**,
 \Rightarrow test of $c_0' \beta_0 = 0$ **over rejects**.

See Liu and Yang (2015b) or Lecture 4 for details on this issue. colorblueA Monte Carlo comparison of QML and GLS-GM estimators is of interest.

Neighborhood Crime. In illustrating the applications of spatial cross-sectional models, Anselin (1988, p.187) used the neighborhood crime data corresponding to 49 contiguous neighborhood in Columbus, Ohio, in 1980. These neighborhood correspond to census tracts, where

- `Crime`: the response variable pertaining to the combined total of residential burglaries and vehicle thefts per thousand household in the neighborhood.
- `Income` and housing values (`House`), are the explanatory variables both in thousand dollars.
- A dummy variable `East` indicates whether the 'neighborhood' in the east or west of a main north-south transportation axis.

The estimation results for the SLR-SE model are summarized in Table 2.1.

- Both `Income` and `House` have significant and negative effects on `Crime`.
- Data show a strong positive spatial error correlation in `Crime` among the 'neighbors' in Columbus, Ohio, in 1980.

Table 2.1. Estimation of SLR-SE Model: Neighborhood Crime

	QMLE	se	t-Ratio	rse	rt-Ratio
constant	59.8924	5.3662	11.1611	5.3662	11.1611
income	-0.9413	0.3306	-2.8477	0.3306	-2.8477
hvalue	-0.3023	0.0905	-3.3407	0.0905	-3.3407
σ^2	95.5737	19.8735	4.8091	27.1596	3.5190
ρ	0.5618	0.1339	4.1963	0.1343	4.1835

- The dummy variable `East` can be added to the model to see whether there is a significant difference between east and west in neighborhood crime.
- Spatial Durbin terms (of `Income` and/or `House`) can be added to the model to 'see' if there are contextual effects on `Crime`.
- There may be model specifications that can better reflect 'spillover effects' of crimes in Columbus, Ohio.
- See [Lab1](#) for details on Matlab implementation of the estimation and inference procedures introduced.

Boston House Price. The data, from Harrison and Rubinfeld (1978), corrected and augmented with longitude and latitude by Gilley and Pace (1996), contains 506 observations (1 observation per census tract) from Boston Metropolitan Statistical Area ([Click for Data](#)). The variables are:

- MEDV: the median value (corrected) of owner-occupied homes in 1000's;
- crime: per capita crime rate by town;
- zoning: proportion of residential land zoned for lots over 25,000 square feet;
- industry: proportion of non-retail business acres per town;
- charlesr: Charles River dummy variable (= 1 if tract bounds river; 0 o.w.);
- nox: nitric oxides concentration (parts per 10 million);
- room: average number of rooms per dwelling;
- houseage: proportion of owner-occupied units built prior to 1940;
- distance: weighted distances to five Boston employment centres;
- access: index of accessibility to radial highways;
- taxrate: full-value property-tax rate per 10,000;
- ptratio: pupil-teacher ratio by town;
- blackpop: $1000(Bk - 0.63)^2$ where Bk is the proportion of blacks by town;
- lowclass: lower status of the population proportion.

The spatial weight matrix is constructed using the Euclidean distance in terms of longitude and latitude. A threshold distance e.g., 0.05, is chosen, which gives a W_n matrix with 19.08% non-zero elements.

The results from fitting a SLR-SE model is summarized in Table 2.2.

- The variables `crime`, `noxsq`, `distance`, `taxrate`, `ptratio`, and `lowclass` all have strong (highly significant) negative effects on house price.
- The variables `zoning`, `rooms2`, `access`, and `blackpop` all have strong positive effects on house price.
- Data show a strong positive SE correlation among neighboring regions.
- SD effects can be added, and their significance can be inferred.
- Alternative model specifications can be used.
- See [Lab2](#) for details on Matlab implementation of the estimation and inference procedures introduced.

Table 2.2. Estimation of SED Model: Boston House Price (MEDV)

	QMLE	se	t-Ratio	rse	rt-Ratio
constant	29.6250	5.4956	5.3907	5.4956	5.3907
crime	-0.1318	0.0276	-4.7693	0.0276	-4.7693
zoning	0.0379	0.0141	2.6887	0.0141	2.6887
industry	-0.0139	0.0729	-0.1909	0.0729	-0.1909
charlesr	-0.4975	0.8794	-0.5658	0.8794	-0.5658
noxsq	-19.2666	5.2686	-3.6568	5.2686	-3.6568
rooms2	4.2812	0.3643	11.7516	0.3643	11.7516
houseage	-0.0259	0.0139	-1.8604	0.0139	-1.8604
distance	-1.6095	0.3021	-5.3276	0.3021	-5.3276
access	0.3174	0.0767	4.1407	0.0767	4.1407
taxrate	-0.0130	0.0036	-3.6137	0.0036	-3.6137
ptratio	-0.6143	0.1523	-4.0344	0.1523	-4.0344
blackpop	0.0106	0.0031	3.4261	0.0031	3.4261
lowclass	-0.4270	0.0514	-8.2999	0.0514	-8.2999
σ^2	14.9219	0.9697	15.3874	1.7700	8.4306
ρ	0.6947	0.0420	16.5461	0.0420	16.5332

2.3. SLR Model with SL Dependence

The model. The spatial lag (SL) dependence model takes the form:

$$Y_n = \lambda W_n Y_n + X_n \beta + \epsilon_n, \quad (2.14)$$

where Y_n , X_n , and W_n are as in (2.1). The errors $\epsilon_{n,i}$ are iid(0, σ^2).

- The term $\lambda W_n Y_n$ says that the dependent variable of a specific spatial unit may depend on the dependent variables of other spatial units.
- This model captures the possible **endogenous interaction effects**.
- A major difference between the SL and SE models is that the spatial interactions in SE model changes only the variance of Y_n , whereas in SL model, it changes both the mean and the variance of Y_n :

$$\text{SE model: } E(Y_n) = X_n \beta, \quad \text{Var}(Y_n) = \sigma^2 B_n^{-1}(\rho) B_n'^{-1}(\rho),$$

$$\text{SL model: } E(Y_n) = A_n^{-1}(\lambda) X_n \beta, \quad \text{Var}(Y_n) = \sigma^2 A_n^{-1}(\lambda) A_n'^{-1}(\lambda),$$

where $A_n(\lambda) = I_n - \lambda W_n$, **with its inverse being assumed to exist**.

Durbin-SL model. Similar to the SE model, the SL model (2.14) can also be extended by adding a spatial Durbin term $W_n X_n^*$, where X_n^* contains a subset of regressors (excluding, e.g., the constant term), giving the so-called **Durbin-SL model** of the form (Elhorst 2014, p.7):

$$Y_n = \lambda W_n Y_n + X_n \beta + W_n X_n^* \beta^* + \epsilon_n. \quad (2.15)$$

By defining a new regressor matrix $\mathbb{X} = [X_n, W_n X_n^*]$, and a new vector of regression coefficients $\beta = (\beta', \beta^{*'})'$,

- Durbin-SL model (2.15) has an identical form as the regular SL model, and all the estimation and inference methods remain the same.
- However, a problem of particular interest is to infer the significance of spatial Durbin effect as in the Durbin-SE model, i.e., whether the data provide sufficient evidence to infer $\beta^* \neq 0$,
- which can be carried out based on confidence intervals or tests for covariate effects. The latter is to be introduced in Lecture 3.

2.3.1. QML estimation of SL model

For ease of exposition, we proceed with Model (2.14). Using the matrix $A_n(\lambda)$, Model (2.14) has a reduced form:

$$A_n(\lambda)Y_n = X_n\beta + \epsilon_n.$$

Assuming $\epsilon_{n,i}$ are iid $N(0, \sigma^2)$, the joint pdf of ϵ_n is

$$(2\pi\sigma^2)^{-\frac{n}{2}} \exp\left(-\frac{1}{2\sigma^2}\epsilon_n'\epsilon_n\right),$$

which gives the joint pdf of Y_n (or likelihood function) as the **Jacobian** of transformation ($\epsilon_n \rightarrow Y_n$) equals $|\frac{\partial \epsilon_n}{\partial Y_n}| = |A_n(\lambda)|$, **assumed to be positive**.

Thus, the log-likelihood function of $\theta = (\beta', \sigma^2, \lambda)'$ is

$$\begin{aligned} \ell_n(\theta) = & -\frac{n}{2} \log(2\pi\sigma^2) + \log |A_n(\lambda)| \\ & - \frac{1}{2\sigma^2} [A_n(\lambda)Y_n - X_n\beta]' [A_n(\lambda)Y_n - X_n\beta]. \end{aligned} \quad (2.16)$$

Maximizing $\ell_n(\theta)$ gives the MLE $\hat{\theta}_n$ of θ if $\epsilon_{n,i}$ are truly iid $N(0, \sigma^2)$, otherwise the QMLE if $\epsilon_{n,i}$ are merely iid $(0, \sigma^2)$.

Similar to the case of SE model, the MLE or QMLE $\hat{\theta}_n$ can be obtained by solving the score-based estimating equations $S_n(\theta) = 0$, where

$$S_n(\theta) = \frac{\partial}{\partial \theta} \ell_n(\theta) = \begin{cases} \frac{1}{\sigma^2} X_n' \epsilon_n(\beta, \lambda), \\ \frac{1}{2\sigma^4} \epsilon_n'(\beta, \lambda) \epsilon_n(\beta, \lambda) - \frac{n}{2\sigma^2}, \\ \frac{1}{\sigma^2} Y_n' W_n' \epsilon_n(\beta, \lambda) - \text{tr}[F_n(\lambda)], \end{cases} \quad (2.17)$$

$\epsilon_n(\beta, \lambda) = A_n(\lambda) Y_n - X_n \beta$, and $F_n(\lambda) = W_n A_n^{-1}(\lambda)$. Thus, the process of obtaining $\hat{\theta}_n$ can be simplified:

- Solving the first two sets of equations in (2.17) for a given λ , we obtain the constrained QMLEs for β and σ^2 , letting $M_n = I_n - X_n(X_n' X_n)^{-1} X_n'$:

$$\tilde{\beta}_n(\lambda) = (X_n' X_n)^{-1} X_n' A_n(\lambda) Y_n, \quad \tilde{\sigma}_n^2(\lambda) = \frac{1}{n} Y_n' A_n'(\lambda) M_n A_n(\lambda) Y_n. \quad (2.18)$$

- Substituting $\tilde{\beta}_n(\lambda)$ and $\tilde{\sigma}_n^2(\lambda)$ back into (2.16) for β and σ^2 , we obtain the partially maximized or the concentrated loglikelihood of λ :

$$\ell_n^c(\lambda) = -\frac{n}{2} [\log(2\pi) + 1] - \frac{n}{2} \log \hat{\sigma}_n^2(\lambda) + \log |A_n(\lambda)|. \quad (2.19)$$

- Maximizing $\ell_n^c(\lambda)$ gives $\hat{\lambda}_n$, $\hat{\beta}_n \equiv \tilde{\beta}_n(\hat{\lambda}_n)$, $\hat{\sigma}_n^2 \equiv \tilde{\sigma}_n^2(\hat{\lambda}_n)$, and hence $\hat{\theta}_n$.

A similar set of notation is followed, e.g., $A_n \equiv A_n(\lambda_0)$, and $F_n \equiv F_n(\lambda_0)$.

Theorem 2.2. Under regularity conditions, we have $\hat{\theta}_n \xrightarrow{p} \theta_0$, and

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{D} N(\theta_0, \lim_{n \rightarrow \infty} n \mathcal{J}_n^{-1} \mathcal{I}_n \mathcal{J}_n^{-1}), \quad (2.20)$$

(Lee 2004), where $\mathcal{J}_n = -E[\frac{\partial}{\partial \theta'} \mathbf{S}_n(\theta_0)]$ and $\mathcal{I}_n = \text{Var}[\mathbf{S}_n(\theta_0)]$, with

$$\mathcal{J}_n = \begin{pmatrix} \frac{1}{\sigma_0^2} X_n' X_n & 0 & \frac{1}{\sigma_0} X_n' \eta_n \\ 0 & \frac{n}{2\sigma_0^4} & \frac{1}{\sigma_0^2} \text{tr}(F_n) \\ \frac{1}{\sigma_0} \eta_n' X_n & \frac{1}{\sigma_0^2} \text{tr}(F_n) & \eta_n' \eta_n + \text{tr}(F_n^s F_n) \end{pmatrix}, \text{ and} \quad (2.21)$$

$$\mathcal{I}_n = \begin{pmatrix} \frac{1}{\sigma_0^2} X_n' X_n & \frac{1}{2\sigma_0^3} \gamma_0 X_n' \iota_n & \frac{1}{\sigma_0} X_n' \eta_n + \frac{1}{\sigma_0} \gamma_0 X_n' f_n \\ \sim & \frac{n}{2\sigma_0^4} + \frac{n}{4\sigma_0^4} \kappa_0 & \frac{1}{\sigma_0^2} \text{tr}(F_n) + \frac{1}{2\sigma_0^2} \gamma_0 \iota_n' \eta_n + \frac{1}{2\sigma_0^2} \kappa_0 \text{tr}(F_n) \\ \sim & \sim & \eta_n' \eta_n + \text{tr}(F_n^s F_n) + \kappa_0 f_n' f_n + 2\gamma_0 f_n' \eta_n \end{pmatrix}, \quad (2.22)$$

where $f_n = \text{diagv}(F_n)$, $F_n^s = F_n + F_n'$, $\eta_n = \sigma_0^{-1} G_n X_n \beta_0$, and γ_0 and κ_0 are the skewness and excess kurtosis of $\epsilon_{n,i}$.

The results (2.20)-(2.22) provide QML-based statistical inferences concerning the parameters of the SLR model with SL dependence.

- Again, \mathcal{I}_n can be estimated by the plug-in estimator $\mathcal{I}_n(\hat{\theta}_n)$, or simply by its sample counterpart $-\frac{\partial}{\partial \theta} \mathcal{S}_n(\theta)|_{\theta=\hat{\theta}_n}$.
- The variance of the score \mathcal{I}_n can be consistently estimated by the plug-in method, i.e., plugging
 - $\hat{\theta}_n$ in \mathcal{I}_n for θ_0 , and
 - $\hat{\gamma}_n$ and $\hat{\kappa}_n$ for γ_0 and κ_0 ,
 - where $\hat{\gamma}_n$ and $\hat{\kappa}_n$ are the sample skewness and excess kurtosis of the estimated errors $\hat{\epsilon}_n = \epsilon_n(\hat{\beta}_n, \hat{\lambda}_n) = A_n(\hat{\lambda}_n) Y_n - X_n \hat{\beta}_n$.
- These results give the estimates of robust standard errors of the QMLE $\hat{\theta}_n$ – robust against nonnormality of the error distribution.
- When it is known that ϵ_n is normally distributed, then $\mathcal{I}_n = \mathcal{J}_n$, and $\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{D} N(\theta_0, \lim_{n \rightarrow \infty} n\mathcal{J}_n^{-1})$.

The added regressor $W_n Y_n$ in the SLD model (2.14) is endogenous, as

$$E[(W_n Y_n)' \epsilon_n] = \sigma_0^2 \text{tr}(F_n(\lambda_0)) \neq 0,$$

i.e., the elements of $W_n Y_n$ are correlated with the elements of ϵ_n . This can easily be seen from the expression $W_n Y_n = F_n(\lambda_0) X_n \beta_0 + F_n(\lambda_0) \epsilon_n$, which follows from the reduced form of (2.14): $Y_n = A_n^{-1}(\lambda_0) X_n \beta + A_n^{-1}(\lambda_0) \epsilon_n$.

- Therefore, OLS estimate of $\vartheta = (\beta', \lambda)'$ is not consistent.
- If W_n is row normalized and $|\lambda| < 1$, then $(I_n - \lambda W_n)^{-1} = \sum_{i=0}^{\infty} \lambda^i W_n^i$,
 \Rightarrow **instrumental variables (IVs) for $W_n Y_n$** : $W_n X_n, W_n^2 X_n, \dots$,
 \Rightarrow **linear moments**: $[X_n, Q_n]' \epsilon_n(\vartheta)$,
 - $\epsilon_n(\vartheta) = A_n(\lambda) Y_n - X_n \beta$,
 - Q_n contains columns of $[W_n X_n, W_n^2 X_n, \dots]$, linearly independent of X_n .
- For $n \times n$ matrices P_{jn} with $\text{tr}(P_{jn}) = 0$, $E(\epsilon_n' P_{jn} \epsilon_n) = \text{tr}(P_{jn} E(\epsilon_n \epsilon_n')) = 0$,
 \Rightarrow **quadratic moments**: $\epsilon_n'(\vartheta) P_{jn} \epsilon_n(\vartheta)$, $j = 1, \dots, m$.

Intuitions: Note that $W_n Y_n = F_n(\lambda_0) X_n \beta_0 + F_n(\lambda_0) \epsilon_n$.

- The chosen Q_n is correlated with $F_n X_n \beta_0$ but uncorrelated with ϵ_n ,
 $\Rightarrow Q$ instruments the mean of $W_n Y_n$;
- $P_{jn} \epsilon_n$ is uncorrelated with ϵ_n , and thus it instruments the error of $W_n Y_n$, if P_{jn} is chosen such that $P_{jn} \epsilon_n$ is correlated with $F_n \epsilon_n$,
 $\Rightarrow P_{jn}$ can be W_n , $W_n^2 - \frac{1}{n} \text{tr}(W_n^2) I_n$, etc.

Letting $Q_n = (X_n, Q_n)$, the **GMM estimator** of ϑ_0 is

$$\tilde{\vartheta}_n = \text{argmin } \mathbf{g}'_n(\vartheta) \Omega_n \mathbf{g}_n(\vartheta),$$

where $\mathbf{g}_n(\vartheta) = \{\epsilon'_n(\vartheta) Q_n, \epsilon'_n(\vartheta) P_{1n} \epsilon_n(\vartheta), \dots, \epsilon'_n(\vartheta) P_{mn} \epsilon_n(\vartheta)\}'$, and Ω_n is the GMM weight matrix. The asymptotic VC matrix of $\tilde{\vartheta}_n$ is given as:

$$\text{AVar}(\tilde{\vartheta}_n) = (\Sigma'_n \Omega_n \Sigma_n)^{-1} (\Sigma'_n \Omega_n \Gamma_n \Omega_n \Sigma_n) (\Sigma'_n \Omega_n \Sigma_n)^{-1},$$

where $\Gamma_n = \text{Var}[\mathbf{g}_n(\vartheta_0)]$ and $\Sigma_n = -E[\frac{\partial}{\partial \vartheta'} \mathbf{g}_n(\vartheta_0)]$, with exact expressions:

$$\Sigma_n = \begin{pmatrix} Q_n' X_n & Q_n' F_n X_n \beta_0 \\ 0 & \sigma_0^2 \text{tr}(P_{1n}^s F_n) \\ \vdots & \vdots \\ 0 & \sigma_0^2 \text{tr}(P_{mn}^s F_n) \end{pmatrix}, \quad (2.23)$$

$$\Gamma_n = \begin{pmatrix} \sigma_0^2 Q_n' Q_n & \sigma_0^3 \gamma_0 Q_n' \omega_{nm} \\ \sigma_0^3 \gamma_0 \omega_{nm}' Q_n & \sigma_0^4 (\Lambda_{mn} + \kappa_0 \omega_{nm}' \omega_{nm}) \end{pmatrix}, \quad (2.24)$$

where $P_{kn}^s = P_{kn}' + P_{kn}$, $k = 1, \dots, m$, $\omega_{nm} = \{\text{diagv}(P_{1n}), \dots, \text{diagv}(P_{mn})\}$, and $\Lambda_{mn} = \{\text{tr}(P_{jn} P_{kn}^s), j, k = 1, \dots, m\}$.

- Simplest GMM: $\Omega_n = I_n$;
- Optimal GMM: $\Omega_n = \Gamma_n^{-1}$, not feasible as Γ_n contains σ_0^2 , γ_0 and κ_0 ;
- Feasible optimal GMM: $\Omega_n = \tilde{\Gamma}_n^{-1}$, where $\tilde{\Gamma}_n$ is a 'consistent estimate' of Γ_n , based on initial consistent estimate of ϑ_0 ;
- Best OPGMM: choose 'best' moment functions, . . . (see Lee, 2007).

A simple choice for $\tilde{\Gamma}_n$ is $\tilde{\Gamma}_{2SLS}$ based on the 2SLS estimation:

- (i) let $Z_n = (X_n, W_n Y_n)$, and compute the 2SLSE of ϑ_0 :

$$\tilde{\vartheta}_{2SLS} = [Z_n' Q_n (Q_n' Q_n)^{-1} Q_n' Z_n]^{-1} Z_n' Q_n (Q_n' Q_n)^{-1} Q_n' Y_n,$$

- (ii) compute the 2SLE residuals $\tilde{\epsilon}_{2SLS} = A_n(\tilde{\lambda}_{2SLS}) - X_n \tilde{\beta}_{2SLS}$, and the sample variance, skewness and excess kurtosis of $\tilde{\epsilon}_{2SLS}$ to give consistent estimates of σ^2 , γ_0 and κ_0 .

The feasible OGMM estimator of ϑ_0 is

$$\tilde{\vartheta}_n^\circ = \operatorname{argmin} \mathbf{g}'_n(\vartheta) \tilde{\Gamma}_{2SLS}^{-1} \mathbf{g}_n(\vartheta),$$

and a consistent estimate of the asymptotic VC matrix of $\tilde{\vartheta}_n^\circ$ is

$$(\tilde{\Sigma}'_{2SLS} \tilde{\Gamma}_{2SLS}^{-1} \tilde{\Sigma}_{2SLS})^{-1}.$$

- For more details on GMM estimation of SL model, see Lee (2007).
- A thorough Monte Carlo comparison of QMLE and GMME are desirable, based on 'strong' or 'weak' instruments.

2.3.3. Finite sample performance of QMLE of SL model

Like the case of SE dependence, the existence of SL dependence also causes the QMLE of the spatial lag parameter to be biased.

- Yang (2015) presents a rigorous study on the finite sample properties of the QML estimator of λ .
- The QMLE $\hat{\lambda}_n$ is downward biased – the denser is the spatial weight matrix the more its is downward biased.
- Yang (2015) proposes a general method of bias correction, which is shown to be quite effective in removing the bias.
- Liu and Yang (2015b) show that the usual t -statistics for covariate effects tend to reject the null hypothesis of ‘no effect’ too often. They proposed finite sample improved test statistics based on the bias-correction method of Yang (2015).
- These methods will be introduced in the subsequent lectures.

Boston House Price. See Sec. 2.2.4 for detailed description of the data and the construction of spatial weight matrix.

The results from fitting a SLR-SL model is summarized in Table 2.3.

- Similar to the SLR-SE model, `crime`, `noxsq`, `distance`, `taxrate`, `ptratio`, and `lowclass` all have strong negative effects on house price.
- The variables `zoning`, `rooms2`, `access`, and `blackpop` all have strong positive effects on house price.
- Data show a strong positive SL dependence among neighboring regions.
- SD effects can be added, and their significance can be inferred.
- Alternative model specifications can be used.
- QMLE-bc (bias-corrected QMLE of Yang 2015) results are slightly different.
- See [Lab2](#) for details on Matlab implementation of the estimation and inference procedures introduced.

Table 2.3. QML Estimation of SL Model: Boston House Price

	QMLE	rse	t-Ratio	QMLE-bc	rse-bc	t-Ratio-bc
constant	14.5396	5.0687	2.8685	13.4682	5.0337	2.6756
crime	-0.0831	0.0300	-2.7678	-0.0819	0.0300	-2.7326
zoning	0.0448	0.0124	3.6167	0.0447	0.0124	3.6151
industry	0.0353	0.0555	0.6368	0.0361	0.0554	0.6506
charlesr	1.1181	0.7850	1.4243	1.0414	0.7835	1.3291
noxsq	-11.4788	3.5190	-3.2620	-11.1715	3.5104	-3.1824
rooms2	3.7066	0.3800	9.7543	3.7016	0.3794	9.7564
houseage	0.0021	0.0119	0.1733	0.0021	0.0119	0.1792
distance	-1.2240	0.1842	-6.6431	-1.2117	0.1838	-6.5921
access	0.2553	0.0604	4.2258	0.2529	0.0603	4.1921
taxrate	-0.0110	0.0034	-3.2225	-0.0109	0.0034	-3.2075
prratio	-0.5349	0.1247	-4.2880	-0.5145	0.1242	-4.1427
blackpop	0.0078	0.0024	3.2216	0.0078	0.0024	3.1968
lowclass	-0.3679	0.0483	-7.6215	-0.3602	0.0481	-7.4952
σ^2	18.3358	2.2937	7.9938	18.2882	2.2845	8.0053
λ	0.3833	0.0399	9.6044	0.4020	0.0386	10.4204

2.4. SLR Model with SLE Dependence

The model. Adding both spatial lag and error (SLE) into the linear regression models, we have a more general SLR model:

$$Y_n = \lambda W_{1n} Y_n + X_n \beta + u_n, \quad u_n = \rho W_{2n} u_n + \epsilon_n. \quad (2.25)$$

It is also called the SARAR model in the literature, which emphasizes that the model contains a spatial autoregressive (SAR) term in response and a SAR term in error in line with the terms used in time series model.

- As for the SE and SL models, a spatial Durbin term, $W_{3n} X_n^* \beta^*$, can also be added into the model to capture the so-called **contextual effects**.
- Again, it is of interest to infer if $\beta^* = 0$.
- The W matrices are in general different to capture different types of spatial interactions corresponding to SL, SE and SD effects, but they are allowed to be the same as far as the methods are concerned.
- For ease of exposition, we work with Model (2.25), thinking that the SD term, if any, has already been merged into the covariates effect $X_n \beta$.

2.4.1. QML estimation of SLE model.

The model (2.25) has the reduced form:

$$B_n(\rho)A_n(\lambda)Y_n = B_n(\rho)X_n\beta + \epsilon_n.$$

where $A_n(\lambda) = I_n - \lambda W_{1n}$ and $B_n(\rho) = I_n - \rho W_{2n}$ as defined earlier.

- The Jacobian of the transformation ($\epsilon_n \rightarrow Y_n$) is $|B_n(\rho)A_n(\lambda)|$.
- The quasi Gaussian loglikelihood function of $\theta = (\beta', \sigma^2, \lambda, \rho)'$ is

$$\begin{aligned} \ell_n(\theta) = & -\frac{n}{2} \log(2\pi\sigma^2) + \log |A_n(\lambda)| + \log |B_n(\rho)| \\ & - \frac{1}{2\sigma^2} [\mathbb{Y}_n(\delta) - \mathbb{X}_n(\rho)\beta]' [\mathbb{Y}_n(\delta) - \mathbb{X}_n(\rho)\beta], \end{aligned} \quad (2.26)$$

where $\delta = (\lambda, \rho)'$, $\mathbb{X}_n(\rho) = B_n(\rho)X_n$, and $\mathbb{Y}_n(\delta) = B_n(\rho)A_n(\lambda)Y_n$.

- Maximizing $\ell_n(\theta)$ gives the MLE $\hat{\theta}_n$ of θ if $\{\epsilon_i\}$ are iid normal. Otherwise, $\hat{\theta}_n$ is the QMLE of θ .
- Assumptions: $|A_n(\lambda)| > 0$, $|B_n(\rho)| > 0$, and $A_n^{-1}(\lambda)$ and $B_n^{-1}(\rho)$ exist.

The (quasi) score function, $S_n(\theta) = \frac{\partial}{\partial \theta} \ell_n(\theta)$, has the form:

$$S_n(\theta) = \begin{cases} \frac{1}{\sigma^2} \mathbb{X}'_n(\rho) \epsilon_n(\beta, \delta), \\ \frac{1}{2\sigma^4} \epsilon'_n(\beta, \lambda) \epsilon_n(\beta, \delta) - \frac{n}{2\sigma^2}, \\ \frac{1}{\sigma^2} \mathbf{Y}'_n \mathbf{W}'_{1n} \mathbf{B}'_n(\rho) \epsilon_n(\beta, \delta) - \text{tr}[\mathbf{F}_n(\lambda)], \\ \frac{1}{\sigma^2} \epsilon'_n(\beta, \delta) \mathbf{G}_n(\rho) \epsilon_n(\beta, \delta) - \text{tr}[\mathbf{G}_n(\rho)], \end{cases} \quad (2.27)$$

• $\epsilon_n(\beta, \delta) = \mathbb{Y}_n(\delta) - \mathbb{X}_n(\rho)\beta$, $F_n(\lambda) = \mathbf{W}_{1n} \mathbf{A}_n^{-1}(\lambda)$, and $\mathbf{G}_n(\rho) = \mathbf{W}_{2n} \mathbf{B}_n^{-1}(\rho)$.

Given δ , solving the first two components of the quasi score equations, $S_n(\theta) = 0$, we obtain the constrained (Q)MLEs of β and σ^2 :

$$\tilde{\beta}_n(\delta) = [\mathbb{X}'_n(\rho) \mathbb{X}_n(\rho)]^{-1} \mathbb{X}'_n(\rho) \mathbb{Y}_n(\delta), \quad (2.28)$$

$$\tilde{\sigma}_n^2(\delta) = \frac{1}{n} \mathbb{Y}'_n(\delta) \mathbb{M}_n(\rho) \mathbb{Y}_n(\delta), \quad (2.29)$$

where $\mathbb{M}_n(\rho) = \mathbf{I}_n - \mathbb{X}_n(\rho) [\mathbb{X}'_n(\rho) \mathbb{X}_n(\rho)]^{-1} \mathbb{X}'_n(\rho)$. Substituting $\tilde{\beta}_n(\delta)$ and $\tilde{\sigma}_n^2(\delta)$ back into (2.26) gives the concentrated quasi loglikelihood for δ :

$$\ell_n^c(\delta) = -\frac{n}{2} [\ln(2\pi) + 1] - \frac{n}{2} \ln(\hat{\sigma}_n^2(\delta)) + \ln |\mathbf{A}_n(\lambda)| + \ln |\mathbf{B}_n(\rho)|. \quad (2.30)$$

Maximizing (2.30) gives the QMLE $\hat{\delta}_n$ of δ , and thus the QMLEs of β and σ^2 as $\hat{\beta}_n \equiv \tilde{\beta}_n(\hat{\delta}_n)$ and $\hat{\sigma}_n^2 \equiv \tilde{\sigma}_n^2(\hat{\delta}_n)$. Write $\hat{\theta}_n = (\hat{\beta}_n', \hat{\sigma}_n^2, \hat{\delta}_n')'$.

Plugging $\tilde{\beta}_n(\delta)$ and $\tilde{\sigma}_n^2(\delta)$ into the δ -component of $S_n(\theta)$ and simplifying, we have the **concentrated quasi score (CQS) function** of δ :

$$S_n^c(\delta) = \begin{cases} -\text{tr}(\mathbf{G}_{1n}(\lambda)) + \frac{n\mathbf{Y}'_n(\delta)\mathbf{M}_n(\rho)\bar{\mathbf{F}}_n(\delta)\mathbf{Y}_n(\delta)}{\mathbf{Y}'_n(\delta)\mathbf{M}_n(\rho)\mathbf{Y}_n(\delta)}, \\ -\text{tr}(\mathbf{G}_n(\rho)) + \frac{n\mathbf{Y}'_n(\delta)\mathbf{M}_n(\rho)\mathbf{G}_n(\rho)\mathbf{M}_n(\rho)\mathbf{Y}_n(\delta)}{\mathbf{Y}'_n(\lambda)\mathbf{M}_n(\rho)\mathbf{Y}_n(\delta)}, \end{cases} \quad (2.31)$$

where $\bar{\mathbf{F}}_n(\delta) = \mathbf{B}_n(\rho)\mathbf{F}_n(\lambda)\mathbf{B}_n^{-1}(\rho)$. **Maximizing $\ell_n^c(\delta) \Leftrightarrow$ solving $S_n^c(\delta) = 0$.**

The CQS function $S_n^c(\delta)$ is the key expression for

- deriving the score-based tests for the spatial effects,
- for performing bias-correction on the QMLE $\hat{\delta}_n$,

to be introduced in the subsequent lectures.

Theorem 2.3. Under some regularity conditions, we have $\hat{\theta}_n \xrightarrow{p} \theta_0$, and

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{D} N(\theta_0, \lim_{n \rightarrow \infty} n \mathcal{J}_n^{-1} \mathcal{I}_n \mathcal{J}_n^{-1}), \quad (2.32)$$

(Jin and Lee 2013), where $\mathcal{J}_n = -E[\frac{\partial}{\partial \theta'} S_n(\theta_0)]$ and $\mathcal{I}_n = \text{Var}[S_n(\theta_0)]$, with

$$\mathcal{J}_n = \begin{pmatrix} \frac{1}{\sigma_0^2} \mathbb{X}'_n \mathbb{X}_n & 0 & \frac{1}{\sigma_0} \mathbb{X}'_n \mu_n & 0 \\ \sim & \frac{n}{2\sigma_0^4} & \frac{1}{\sigma_0^2} \text{tr}(\mathbf{F}_n) & \frac{1}{\sigma_0^2} \text{tr}(\mathbf{G}_n) \\ \sim & \sim & \mu'_n \mu_n + \text{tr}(\bar{\mathbf{F}}_n^s \bar{\mathbf{F}}_n) & \text{tr}(\mathbf{G}_n^s \bar{\mathbf{F}}_n) \\ \sim & \sim & \sim & \text{tr}(\mathbf{G}_n^s \mathbf{G}_n) \end{pmatrix}, \quad (2.33)$$

$$\mathcal{I}_n = \mathcal{J}_n + \begin{pmatrix} 0 & \frac{\gamma_0}{2\sigma_0^3} \mathbb{X}'_n \iota_n & \frac{\gamma_0}{\sigma_0} \mathbb{X}'_n \bar{\mathbf{f}}_n & \frac{\gamma_0}{\sigma_0} \mathbb{X}'_n \mathbf{g}_n \\ \sim & \frac{n\kappa_0}{4\sigma_0^4} & \frac{\kappa_0}{2\sigma_0^2} \text{tr}(\mathbf{F}_n) + \frac{\gamma_0}{2\sigma_0^2} \iota'_n \mu_n & \frac{\kappa_0}{2\sigma_0^2} \text{tr}(\mathbf{G}_n) \\ \sim & \sim & \kappa_0 \bar{\mathbf{f}}'_n \bar{\mathbf{f}}_n + 2\gamma_0 \bar{\mathbf{f}}'_n \mu_n & \kappa_0 \mathbf{g}'_n \bar{\mathbf{f}}_n + \gamma_0 \mathbf{g}'_n \mu_n \\ \sim & \sim & \sim & \kappa_0 \mathbf{g}'_n \mathbf{g}_n \end{pmatrix}, \quad (2.34)$$

where $\mu_n = \sigma_0^{-1} B_n F_n X_n \beta_0$, $\bar{\mathbf{f}}_n = \text{diag}(\bar{\mathbf{F}}_n)$, $\bar{\mathbf{F}}_n^s = \bar{\mathbf{F}}_n + \bar{\mathbf{F}}_n'$, $\bar{\mathbf{F}}_n = \bar{\mathbf{F}}_n(\delta_0) = B_n F_n B_n^{-1}$, and all others quantities are defined earlier.

The results (2.32)-(2.34) form the base for statistical inferences, e.g., confidence intervals, LM tests, Wald tests, for the elements of θ .

- \mathcal{J}_n is estimated by the plug-in estimator $\mathcal{J}_n(\hat{\theta}_n)$, or by $-\frac{\partial}{\partial \theta} \mathbf{S}_n(\theta)|_{\theta=\hat{\theta}_n}$.
- \mathcal{I}_n is estimated by the 'plug-in' estimator as well, i.e., $\mathcal{I}_n(\hat{\theta}_n, \hat{\gamma}_n, \hat{\kappa}_n)$, obtained by plugging in $\hat{\theta}_n$, $\hat{\gamma}_n$ and $\hat{\kappa}_n$,
- $\hat{\gamma}_n$ and $\hat{\kappa}_n$ are the sample skewness and excess kurtosis of the QML residuals $\hat{\epsilon}_n = \mathbb{Y}_n(\hat{\delta}_n) - \mathbb{X}_n(\hat{\rho}_n)\hat{\beta}_n$.
- Square roots of diagonal elements of $\mathcal{J}_n^{-1}(\hat{\theta}_n)\mathcal{I}_n(\hat{\theta}_n, \hat{\gamma}_n, \hat{\kappa}_n)\mathcal{J}_n^{-1}(\hat{\theta}_n)$ give the estimated standard errors of the elements of $\hat{\theta}_n$.

2.4.2. GMM estimation

Lee and Liu (2010) extend the GMM framework for the SL model to a high-order spatial linear regression model, SARAR(p, q), including the SLE model, or SARAR(1, 1), discussed above. The set of moment functions for SARAR(1,1) remains in a similar form as for SL model:

$$\mathbf{g}_n(\vartheta) = \{ \epsilon'_n(\vartheta) \mathbf{Q}_n, \epsilon'_n(\vartheta) \mathbf{P}_{1n} \epsilon_n(\vartheta), \dots, \epsilon'_n(\vartheta) \mathbf{P}_{mn} \epsilon_n(\vartheta) \}' ,$$

except that now $\vartheta = (\beta', \lambda, \rho)'$ and $\epsilon_n(\vartheta) = \mathbf{B}_n(\rho)[\mathbf{A}_n(\lambda)\mathbf{Y}_n - \mathbf{X}_n\beta]$.

Now, letting again $\Sigma_n = -E[\frac{\partial}{\partial \vartheta'} \mathbf{g}_n(\vartheta_0)]$ and $\Gamma_n = \text{Var}[\mathbf{g}_n(\vartheta_0)]$, we have

$$\Sigma_n = \begin{pmatrix} \mathbf{Q}'_n \mathbf{X}_n, & \mathbf{Q}'_n \bar{\mathbf{F}}_n \mathbf{X}_n \beta_0, & 0 \\ 0, & \sigma_0^2 \text{tr}(\mathbf{P}_{1n}^s \bar{\mathbf{F}}_n), & \sigma_0^2 \text{tr}(\mathbf{P}_{1n}^s \mathbf{G}_n) \\ \vdots & \vdots & \vdots \\ 0, & \sigma_0^2 \text{tr}(\mathbf{P}_{mn}^s \bar{\mathbf{F}}_n), & \sigma_0^2 \text{tr}(\mathbf{P}_{mn}^s \mathbf{G}_n) \end{pmatrix}, \quad (2.35)$$

and Γ_n identical in expression as that given in (2.24).

The feasible OGMM estimate of ϑ_0 is thus

$$\tilde{\vartheta}_n = \operatorname{argmin} \mathbf{g}'_n(\vartheta) \tilde{\Gamma}_n^{-1} \mathbf{g}_n(\vartheta)$$

where $\tilde{\Gamma}_n$ is a consistent estimate of Γ_n , which can be obtained based on the generalized 2SLS estimate of Kelejian and Prucha (1998):

- (i) let $Z_n = (X_n, W_n Y_n)$, and compute the G2SLSE of ϑ_0 :

$$\begin{aligned} \tilde{\vartheta}_{\text{G2SLS}} &= [Z'_n B'_n(\tilde{\rho}_n) Q_n (Q'_n Q_n)^{-1} Q'_n B_n(\tilde{\rho}_n) Z_n]^{-1} \\ &\quad Z'_n B'_n(\tilde{\rho}_n) Q_n (Q'_n Q_n)^{-1} Q'_n B_n(\tilde{\rho}_n) Y_n, \end{aligned}$$

where $\tilde{\rho}_n$ is a consistent initial estimator of ρ .

- (ii) compute the G2SLE residuals $\epsilon(\tilde{\vartheta}_{\text{G2SLS}})$, and the sample variance, skewness and excess kurtosis of $\epsilon(\tilde{\vartheta}_{\text{G2SLS}})$ to give consistent estimates of σ_0^2 , γ_0 and κ_0 .

Finally, the IV matrix Q_n can be taken as a subset of linearly independent columns of $\{X_n, W_{1n}X_n, W_{1n}^2X_n, W_{2n}X_n, W_{2n}^2X_n\}$ (containing X_n), and the P_{jn} matrices can be constructed similarly to these for the SL model.

2.4.3. Finite sample performance of the QMLE of SLE model

With both SL and SE effects in the model, the finite sample performance of the QMLEs may be of more concern.

- Liu and Yang (2015b) extended the bias-correction procedure of Yang (2015) from SL model to SLE model. They focus on improving the finite sample performance of t -ratios for covariates effects.
- Their bootstrap methods can be followed for a Monte Carlo comparison of QMLE $\hat{\delta}_n$ and bias-corrected $\hat{\delta}_n$ on their finite sample performance.
- Details on bias-corrected estimation of spatial autocorrelation will be given in Lecture 4.
- A Monte Carlo comparison of QML-type and GMM-type estimators is desired.

Boston House Price. See Sec. 2.2.4 for detailed description of the data and the construction of spatial weight matrix.

The results from fitting a SLR-SLE model is summarized in Table 2.4.

- The conclusions on covariates effects are largely unchanged.
- Interestingly, spatial error effect is strong and positive as in the SLR-SE model, but with the existence of SE effect the SL effects becomes insignificant.
- Alternative model specifications with different types of spatial weight matrices for SL and SE effects may help addressing this issue.
- SD effects can be added, and their significance can be inferred.
- QMLE-bc (bias-corrected QMLE of Yang 2015) results are slightly different.
- See [Lab2](#) for details on Matlab implementation of the estimation and inference procedures introduced.

Table 2.4. Estimation of SLE Model: Boston House Price

	QMLE	rse	t-Ratio	QMLE-bc	rse-bc	t-Ratio-bc
constant	27.8251	5.9648	4.6649	27.8251	5.9648	4.6649
crime	-0.1301	0.0279	-4.6660	-0.1301	0.0279	-4.6660
zoning	0.0390	0.0141	2.7763	0.0390	0.0141	2.7763
industry	-0.0071	0.0723	-0.0976	-0.0071	0.0723	-0.0976
charlesr	-0.3970	0.8775	-0.4524	-0.3970	0.8775	-0.4524
noxsq	-18.5059	5.1765	-3.5750	-18.5059	5.1765	-3.5750
rooms2	4.2958	0.3680	11.6746	4.2958	0.3680	11.6746
houseage	-0.0240	0.0139	-1.7300	-0.0240	0.0139	-1.7300
distance	-1.6254	0.2897	-5.6097	-1.6254	0.2897	-5.6097
access	0.3177	0.0756	4.2047	0.3177	0.0756	4.2047
taxrate	-0.0131	0.0036	-3.6294	-0.0131	0.0036	-3.6294
ptratio	-0.6201	0.1513	-4.0984	-0.6201	0.1513	-4.0984
blackpop	0.0104	0.0031	3.3818	0.0104	0.0031	3.3818
lowclass	-0.4234	0.0521	-8.1350	-0.4234	0.0521	-8.1350
σ^2	15.0920	1.8042	8.3648	15.0920	1.8042	8.3648
λ	0.0569	0.0679	0.8381	0.0506	0.0679	0.7456
ρ	0.6595	0.0593	11.1309	0.6893	0.0593	11.6339

Appendix: Basics on Consistency and Asymptotic Normality

This appendix presents some basics for establishing consistency and asymptotic normality of a QML estimator or an M-estimator. Some Monte Carlo results are also presented in supporting the asymptotic arguments.

We use SLR-SE model to demonstrate typical assumptions required for the asymptotic analysis.

Assumption 1: *The true ρ_0 is in the interior of the compact parameter set \mathcal{P} .*

Assumption 2: *$\{\epsilon_{n,i}\}$ are iid with mean 0, variance σ^2 , and $E|\epsilon_{n,i}|^{4+\delta} < \infty, \forall \delta > 0$.*

Assumption 3: *X_n has full column rank k , its elements are uniformly bounded constants, and $\lim_{n \rightarrow \infty} \frac{1}{n} X_n' B_n'(\rho) B_n(\rho) X_n$ exists and is non-singular for ρ near ρ_0 .*

Assumption 4: *The elements $\{w_{ij}\}$ of W_n are at most of order h_n^{-1} uniformly for all i and j , where h_n can be bounded or divergent but subject to $\lim_{n \rightarrow \infty} \frac{h_n}{n} = 0$; W_n is bounded in both row and column sum norms and its diagonal elements are zero.*

Assumption 5: B_n is non-singular and B_n^{-1} is bounded in both row and column sum norms. Further, $B_n^{-1}(\rho)$ is bounded in either row or column sum norm, uniformly in $\rho \in \mathcal{P}$.

Assumption 6: $\lim_{n \rightarrow \infty} \frac{h_n}{n} [\log |\sigma_0^2 B_n^{-1} B_n'^{-1}| - \log |\sigma_n^2(\rho) B_n^{-1}(\rho) B_n'^{-1}(\rho)|] \neq 0, \forall \rho \neq \rho_0$.

Consistency. Let δ be the parameter vector in the concentrated quasi loglikelihood $\ell_n^c(\delta)$, obtained from the full loglikelihood $\ell_n(\theta)$ by replacing β and σ^2 by their constrained QMLEs.

- Let δ_0 be the true value of θ which takes values in the parameter space Θ . The expectation operator 'E' corresponds the true θ_0 .
- It is only necessary to prove the consistency of $\hat{\delta}_n$ as the consistency of $\hat{\beta}_n$ and $\hat{\sigma}_n$ immediately follow if $\text{plim} \frac{1}{n} X_n' X_n$ exists and is invertible.
- Define $\bar{\ell}_n(\theta) = E[\ell_n(\theta)]$, the expected loglikelihood at a general θ .
- Define $\bar{\ell}_n^c(\delta) = \max_{\beta, \sigma^2} \bar{\ell}_n(\theta)$.

The consistency of $\hat{\delta}_n$ follows, i.e., $\hat{\delta}_n \xrightarrow{P} \delta_0$, if

(a) $\sup_{\delta: d(\delta, \delta_0) \geq \varepsilon} \bar{\ell}_n^c(\delta) < \bar{\ell}_n^c(\delta_0)$, for every $\varepsilon > 0$,

(b) $\sup_{\theta \in \Theta} \frac{1}{n} |\ell_n^c(\delta) - \bar{\ell}_n^c(\delta)| \xrightarrow{P} 0$.

The condition (a) is the so-called identification uniqueness condition for δ_0 which ensures that $\bar{\ell}_n^c(\delta)$ has a identifiably unique maximizer that converges to δ_0 .

This together with condition (b) ensures that the difference between the maximizer $\hat{\theta}_n$ of $\ell_n^c(\delta)$ and the maximizer of $\bar{\ell}_n^c(\delta)$ gets smaller and smaller as n goes large.

See White (1994, Theorem 3.4) or van der Vaar (1998, Theorem 5.7).

For detailed applications of these theorems, see Liu and Yang (2015a) for the case of SE model, Lee (2004) for the case of SL model, and Jin and Lee (2013) for the case of SLE model.

Asymptotic normality. Assume the QMLE $\hat{\theta}_n$ which maximizes $\ell_n(\theta)$, can be equivalently obtained by solving the estimating equation $S_n(\theta) = 0$, where $S_n(\theta) = \frac{\partial}{\partial \theta} \ell_n(\theta)$ is the score function. Assume $\hat{\theta}_n \xrightarrow{P} \theta_0$. Then, by **Taylor series expansion**, we have

$$0 = \frac{1}{\sqrt{n}} S_n(\hat{\theta}_n) = \frac{1}{\sqrt{n}} S_n(\theta_0) + \left[\frac{1}{n} \frac{\partial}{\partial \theta'} S_n(\theta^*) \right] \sqrt{n}(\hat{\theta}_n - \theta_0) + o_p(1),$$

where θ^* lies elementwise between $\hat{\theta}_n$ and θ_0 . The asymptotic normality of $\hat{\theta}_n$ follows if

- (a) $\frac{1}{\sqrt{n}} S_n(\theta_0) \xrightarrow{D} N(0, \lim_{n \rightarrow \infty} \frac{1}{n} \mathcal{I}_n)$,
- (b) $\frac{1}{n} \left[\frac{\partial}{\partial \theta'} S_n(\theta^*) - \frac{\partial}{\partial \theta'} S_n(\theta_0) \right] \xrightarrow{P} 0$, and
- (c) $\frac{1}{n} \left[\frac{\partial}{\partial \theta'} S_n(\theta_0) - E\left(\frac{\partial}{\partial \theta'} S_n(\theta_0)\right) \right] \xrightarrow{P} 0$.

As the elements of $S_n(\theta_0)$ are typically linear or quadratic forms in ϵ_n due to the use of Gaussian quasi likelihood, the result (a) can be proved using the central limit theorem (CLT) for linear-quadratic forms of Kelejian and Prucha (2001), and Cramér-Wold device.

The conditions (b) and (c) can be proved by applying some law of large numbers (LLN).

See for details Liu and Yang (2015a) for the case of SE model, Lee (2004) for SL model, and Jin and Lee (2013) for SLE model.

Clearly, if the above conditions hold, then

$$\begin{aligned} 0 &= \frac{1}{\sqrt{n}} \mathbf{S}_n(\theta_0) + \left[\frac{1}{n} \mathbf{E} \left(\frac{\partial}{\partial \theta'} \mathbf{S}_n(\theta_0) \right) \right] \sqrt{n}(\hat{\theta}_n - \theta_0) + o_p(1) \\ &= \frac{1}{\sqrt{n}} \mathbf{S}_n(\theta_0) - \left[\frac{1}{n} \mathcal{J}_n(\theta_0) \right] \sqrt{n}(\hat{\theta}_n - \theta_0) + o_p(1) \end{aligned}$$

It follows that $\sqrt{n}(\hat{\theta}_n - \theta_0) = \left[\frac{1}{n} \mathcal{J}_n(\theta_0) \right]^{-1} \frac{1}{\sqrt{n}} \mathbf{S}_n(\theta_0) + o_p(1)$. It follows that

$$\text{Var}[\sqrt{n}(\hat{\theta}_n - \theta_0)] = \left[\frac{1}{n} \mathcal{J}_n(\theta_0) \right]^{-1} \text{Var} \left[\frac{1}{\sqrt{n}} \mathbf{S}_n(\theta_0) \right] \left[\frac{1}{n} \mathcal{J}_n(\theta_0) \right]^{-1}.$$

If further $\mathbf{E}[\mathbf{S}_n(\theta_0)] = \mathbf{0}$ or at least $\frac{1}{n} \mathbf{E}[\mathbf{S}_n(\theta_0)] \rightarrow \mathbf{0}$, then

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{D} \mathcal{N}(\mathbf{0}, \lim_{n \rightarrow \infty} n \mathcal{J}_n^{-1} \mathcal{I}_n \mathcal{J}_n^{-1}).$$

Tables A1-A3 presents some Monte Carlo results for the finite sample performance of $\hat{\lambda}_n$, $\hat{\lambda}_n^{\text{bc2}}$ (2nd-order bias-corrected $\hat{\lambda}_n$), and $\hat{\lambda}_n^{\text{bc3}}$ (3rd-order bias-corrected $\hat{\lambda}_n$), of the SLR-SL model. The results reveals:

- $\hat{\lambda}_n$ can be quite biased,
- $\hat{\lambda}_n^{\text{bc2}}$ almost removes the bias,
- $\hat{\lambda}_n^{\text{bc3}}$ does not improve much over $\hat{\lambda}_n^{\text{bc2}}$,
- More results from Yang (2015) show that with a denser spatial weight matrix, the bias of $\hat{\lambda}_n$ becomes larger.
- When sample size increases, all three estimators 'converge' to the true value of λ .
- When sample size is not large, it is necessary to carry out the bias-correction, in particular on the QMLE of the spatial parameter(s).

Table A1. Monte Carlo Mean[rmse](sd) of Estimators of λ in SL Model

λ	n	$\hat{\lambda}_n$	$\hat{\lambda}_n^{bc2}$	$\hat{\lambda}_n^{bc3}$
Queen Contiguity, Normal Errors				
.50	50	.411 [.195](.174)	.492 .175	.497 .175
	100	.459 [.123](.116)	.498 .117	.500 .117
	200	.480 [.078](.076)	.499 .075	.499 .075
	500	.493 [.049](.048)	.501 .048	.501 .048
.25	50	.163 [.222](.204)	.242 .209	.246 .210
	100	.212 [.146](.140)	.248 .142	.250 .143
	200	.231 [.094](.092)	.250 .093	.250 .093
	500	.242 .060	.250 .060	.250 .060
.00	50	-.078 [.229](.216)	-.006 .224	-.003 .226
	100	-.034 [.157](.153)	-.002 .156	-.001 .157
	200	-.018 [.106](.104)	-.000 .105	.000 .105
	500	-.008 [.068](.067)	-.000 .068	-.000 .068
-.25	50	-.317 [.233](.223)	-.255 .236	-.254 .237
	100	-.279 [.164](.161)	-.253 .166	-.253 .166
	200	-.266 [.112](.111)	-.252 .112	-.251 .112
	500	-.256 [.073](.072)	-.250 .073	-.250 .073

Table A2. Monte Carlo Mean[rmse](sd) of Estimators of λ in SL Model

λ	n	$\hat{\lambda}_n$	$\hat{\lambda}_n^{bc2}$	$\hat{\lambda}_n^{bc3}$
Queen Contiguity, Normal Mixture Errors				
.50	50	.420 [.182](.164)	.494 .165	.498 .165
	100	.462 [.120](.114)	.499 .114	.500 .114
	200	.482 [.076](.074)	.500 .074	.500 .074
	500	.492 [.049](.048)	.500 .048	.500 .048
.25	50	.169 [.207](.190)	.241 .195	.244 .195
	100	.213 [.140](.135)	.248 .136	.249 .137
	200	.230 [.092](.090)	.249 .090	.249 .090
	500	.242 .060	.250 .060	.250 .060
.00	50	-.070 [.217](.206)	-.004 .213	-.002 .214
	100	-.032 [.150](.147)	-.002 .150	-.001 .150
	200	-.018 [.104](.103)	-.001 .103	-.001 .103
	500	-.008 [.068](.067)	-.001 .067	-.001 .067
-.25	50	-.314 [.223](.213)	-.258 .224	-.257 .225
	100	-.275 [.155](.153)	-.251 .157	-.250 .157
	200	-.263 [.111](.110)	-.249 .112	-.249 .112
	500	-.257 .072	-.251 .072	-.251 .072

Table A3. Monte Carlo Mean[rmse](sd) of Estimators of λ in SL Model

λ	n	$\hat{\lambda}_n$	$\hat{\lambda}_n^{bc2}$	$\hat{\lambda}_n^{bc3}$
Queen Contiguity, Lognormal Errors				
.50	50	.426 [.163](.146)	.491 .146	.493 .146
	100	.465 [.110](.105)	.498 .105	.498 .105
	200	.482 [.072](.069)	.499 .069	.499 .069
	500	.491 [.047](.046)	.499 .046	.499 .046
.25	50	.179 [.185](.171)	.241 .174	.244 .174
	100	.216 [.128](.124)	.247 [.126](.125)	.248 [.126](.125)
	200	.232 [.087](.085)	.249 .085	.249 .085
	500	.242 [.058](.057)	.249 .057	.249 .057
.00	50	-.067 [.198](.186)	-.011 [.192](.191)	-.008 .192
	100	-.029 [.139](.136)	-.003 .138	-.002 .138
	200	-.017 [.099](.097)	-.002 .098	-.001 .098
	500	-.007 [.065](.064)	-.000 .065	.000 .065
-.25	50	-.307 [.199](.191)	-.258 .198	-.256 .199
	100	-.272 [.142](.140)	-.252 .144	-.251 .144
	200	-.264 [.105](.104)	-.251 .105	-.250 .105
	500	-.256 .070	-.250 .070	-.250 .070

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